CHCNAV

CGI-230 HIGH-PRECISION COMBINED INERTIAL GUIDANCE SYSTEM

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NAVIGATION & INFRASTRUCTURE





HIGH-PRECISION COMBINED INERTIAL GUIDANCE SYSTEM

CGI-230 is a new generation of automotive-grade high-precision tight combination inertial guidance system launched by CHCNAV. Based on the full-system full-frequency point GNSS module and 6-axis tactical IMU, the product adopts CHCNAV's new generation of closely coupled algorithm engine, and through the fusion and solution of GNSS, INS, DR information, it can still provide continuous and high-pre-cision navigation information such as position, speed and attitude in urban canyons, urban overpass, tree-shade, high-speed, park and other satellite signal occlusion or multipath scenarios, which has a higher fixed rate and robustness than the loosely coupled algorithm. The product supports serial port, 100Base-T1 automotive Ethernet, CANFD and other communication

methods; based on Autosar software architecture development, it supports fault messages, UDS diagno-sis, gPTP\CanTsyn, PPS time synchronization scheme, and supports general vehicle, low-speed carrier

Provide stable and reliable high-precision PVAT solutions for logistics and distribution, park cleaning, low-speed robots, RoboTaxi, trunk line logistics, intelligent agricultural machinery and other industries.

AREAS OF APPLICATION





Park Logistics

SPECIFICATIONS

Agricultural farmland



Autonomous Vehicle Driving



Dry logistics

GNSS Performance Indicators				IMU Performance Specifications					
		BDS: B1/B2/B3 GPS: L1/L2/L5 GLONASS: L1/L2 Galileo: E1/E5a/E5b QZSS: L1/L2/L5		Accelerometer bias instability(Allan 1σ)		≤15u	≤15ug		
Signal tracking				Accelerometer angular random walk(Allan 1σ)			0.035m/s√hz		
	QZSS: L1/L2			Fusion output frequency 1			00Hz		
		Single: L1/L2: 1.2m DGPS: 0.4m RTK: 1cm+1ppm (Horizontal) , 2cm+1ppm (Altitude)		Communication Interface					
Positioning accuracy (RMS	S) RTK: 1cm+1			External interface		3×R	Primary connector: 1×power, 3×RS232, 1×PPS, 2×CANFD, 1×100Base-T1, 2×Antenna RF interface		
Heading accuracy (RMS)	0.1°/2 m base	0.1°/2 m baseline					,		
RTK solution frequency	20Hz(max)[1]	20Hz(max)[1]		Environmental					
Speed accuracy (RMS)	0.03m/s	0.03m/s		Operating temperature			-40°C \sim +75°C		
PPS time synchronization	20nc	20ns		Storage temperature			-40°C \sim +85°C		
accuracy (RMS)	20115			Humidity		95%	95% non-condensing		
Cold start time (RMS)	≤35s	≤35s		Protection class		IP52	IP52		
IMU Performance Specifications				Physical Dimensions and Electrical Characteristics					
IMU type	MEMS	MEMS		Power input			9~32V DC		
Gyro output operating rang	ge ±300 °/s	±300 %s					Standard Adaptation 12V DC)		
Gyro bias instability(Allan	1σ) 1.8°/h	1.8°/h		Power consumption			<4W (typical)		
Accelerometer output oper	rating +6a	±6g		Physical dimensions			154×105×35mm		
range (Allan 1 σ)	5			Weight			<400g (without antenna and cable)		
Performance during GNSS outages RMS ^[2]									
GNSS outage duration	Positioning mode	ioning mode Location accuracy		(m/s) Location accura		curacy (m/s)	cy (m/s) Attitude accuracy (°)		
		Horizontal	V	ertical	Horizontal	Vertical	Heading	Attitude	
Os	RTK	0.02		0.03	0.02	0.01	0.08	0.08	
10s	RTK	0.2		0.1	0.05	0.02	0.12	0.09	

Note 1: 20Hz RTK data output, need to use GNSS special RS232_B port. Note 2: GNSS interrupt lost lock test, for passenger car urban tunnel typical test scene test, for reference only. According to different carrier types, different carrier speeds, and different application environments, the test results will vary, subject to the actual scene of the physical test. The values of the parameters listed in this document are all theoretical values or values measured by CHCNAV testers in a specific controlled test environment. The values listed in this document are all theoretical values or values measured by Huatech navigation testers under specific controlled test environments (please see specific instructions), and may be different in actual use due to individual differenc-es in the product, firmware version, use conditions, In actual use, the results may vary to different degrees due to individual product differences, firmware versions, use conditions, parameter values, CHCNAV may adjust and correct the text of this document real time, parameter values and other content. In order to provide the most accurate product information, parameter values, Huatest Navigation may real-time adjustments and corrections to the text of this document, parameter values and other content, in order to mark the actual product of ther content, in order to mark the actual product performance, specifications and other information. Due to real-time changes in product lot Due to real-time changes in product lot and product clorion supply factors, if it is necessary to carry out the aforementioned modifications and adjustments, we will not specifically notify you. Please refer to the real-time information on the official website.

* All specifications are subject to change without notice

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